

日欧GNSSミッション 海洋ロボット開発と運用化への課題 Development of USVs and agendas of their practical use in Japan



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Technical Terms

• 無人航行船

UMV: Unmanned Maritime Vessel

洋上無人探査機

USV: Unmanned Surface Vehicle

• 洋上自律探査機

ASV: Autonomous Surface Vehicle

• 自律型無人探査機

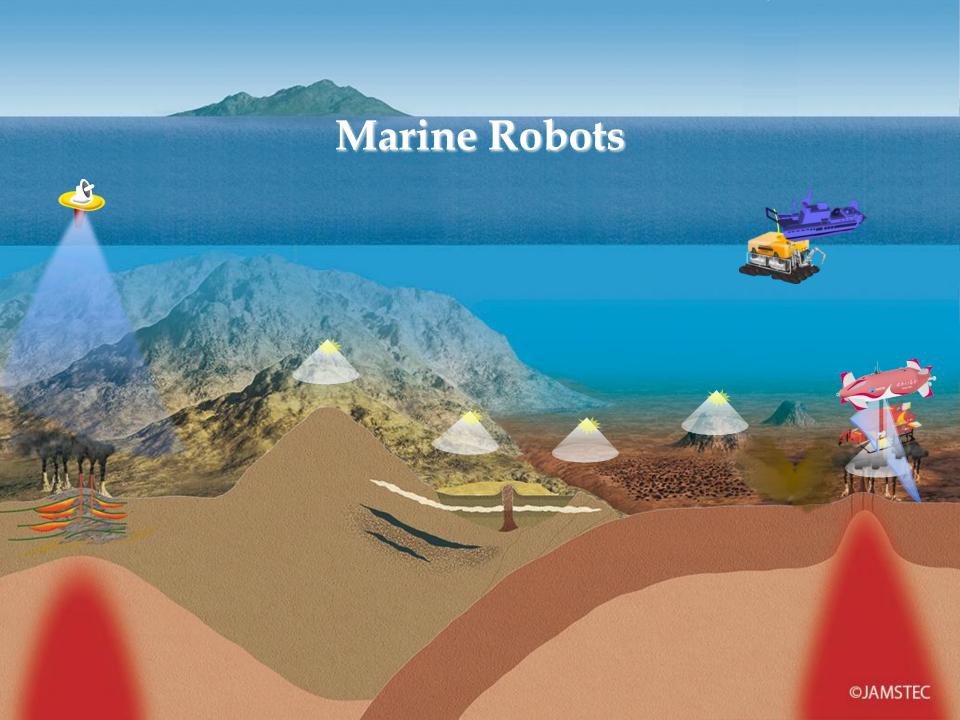
AUV: Autonomous Underwater Vehicle

• 遠隔操縦型無人探査機

ROV: Remotely Operated Vehicle

Surface vehicles

Underwater vehicles



UMVs

Large



? tons Drone ship/ Rolls-Royce



40 m, 135 tons Sea Hunter/ DARFA



4.4 m, 1.5 tons Robotic Boat/ JAMSTEC-Yanmar





90 kg Waveglider / Liquid Robotics



350 kg C-Endurg / ASV

Boat size UMV



3.5 tons C-Worker / ASV



1.7 tons Mariner/ Maritime Robotics



3 tons Kan-chan/ Windy network



1.8 tons **DELPHIS / MES**

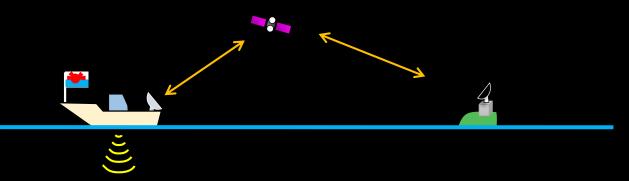


3 tons Mainami / JAMSTEC-MHI

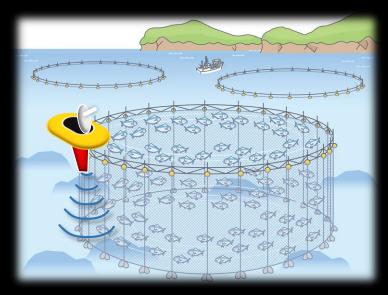


1.5 tons Robotic Boat/ JAMSTEC-Yanmar 5

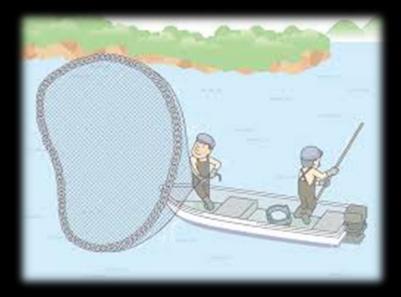
Applications for the fisheries industry



漁船のGNSS・自律認識ハイブリッドによる自動航行 Autonomous cruising of fish boats

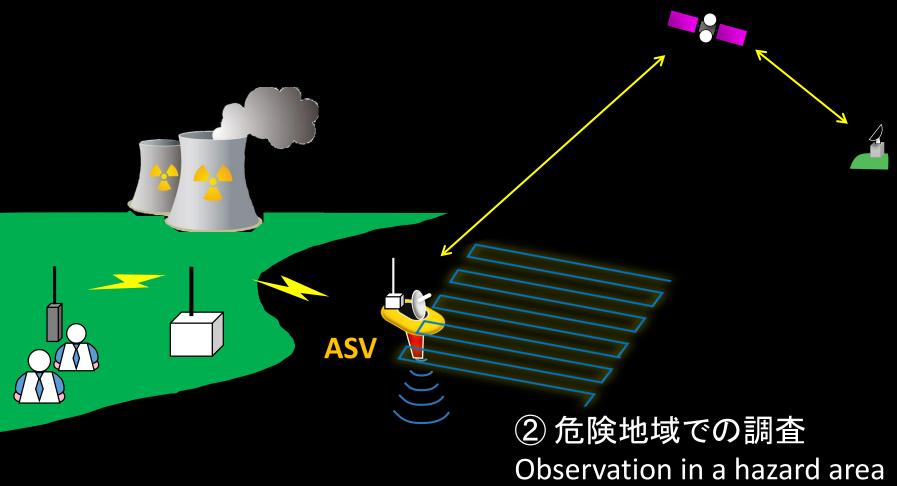


Monitoring of marine farms



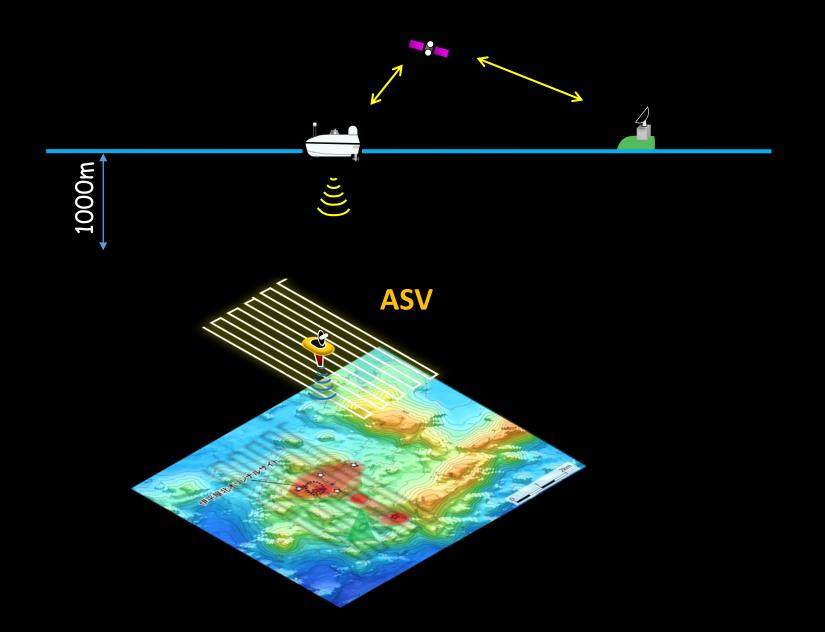
Automatic fixed-point operation

Securing communication and observation in a disaster-stricken region

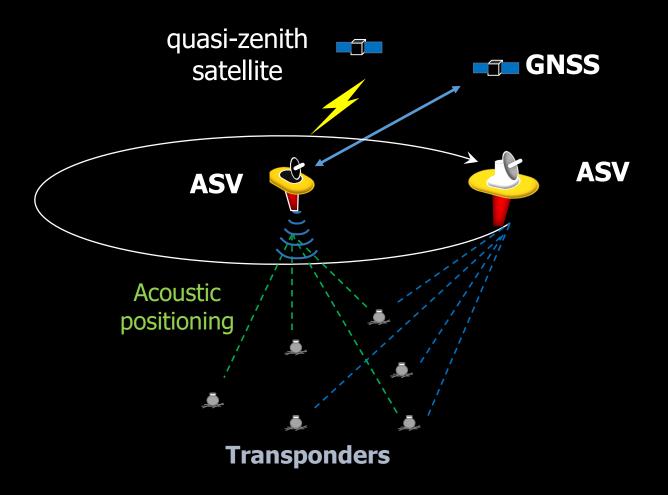


① 被災時の通信確保 securing communication in emergency situations

Creating bathymetry map in shallow water



Observation of crustal movement

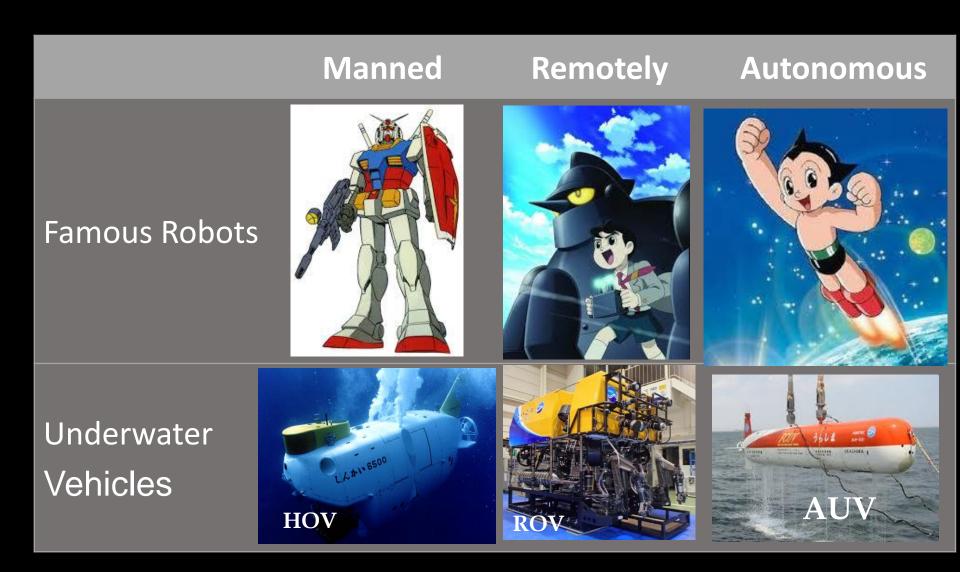


無人船とAUVの同時利用 ASV-AUV applications

Why we need underwater vehicles

ITEMS	Surface	Shallow water	Deep sea
資源開発 Development of resources			Ø
気候変動 Climate change	\square	\square	Ø
環境調査 Environment		otan	\square
港湾点検 Inspection in port and harbor		Ø	
漁業•養殖 Fisheries		Ø	
海洋エネルギー Ocean energy			
輸送 Carrier	\square	`~	

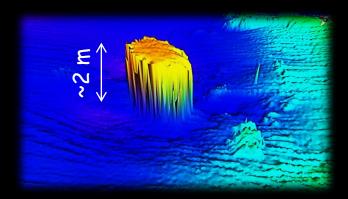
AUV...., What?



AUV enables underwater imaging and...



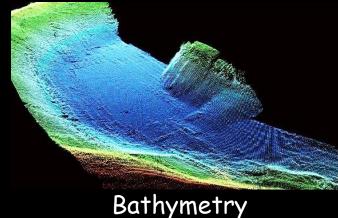
CTD measurement, pH, Co2, ATP, DO, etc.



Laser scanning image



Sonar image



Mosaicing by stereo camera

AUV is higher performance platform but...

Now

A mother vessel positions and monitors AUV(s)

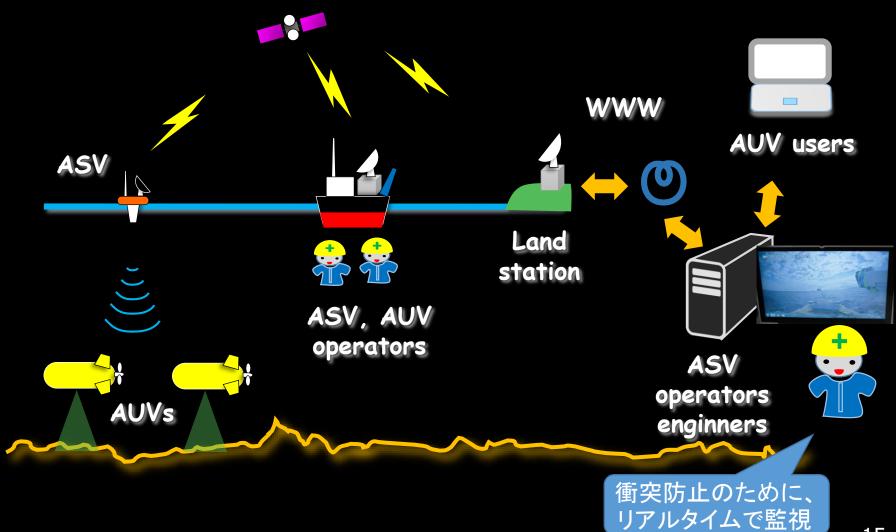


Operation cost of the vessel is about ¥ 5,000,000 / day

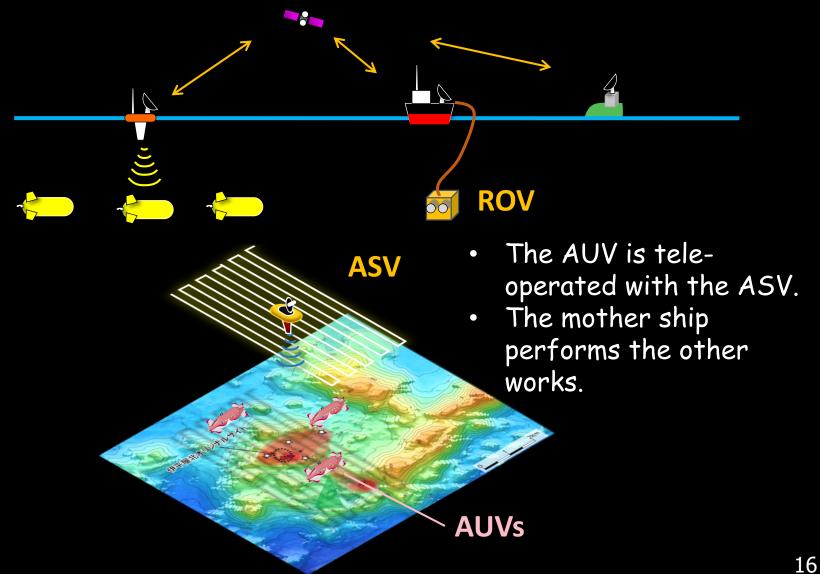


An ASV is a great substitute for a mother vessel

基本的なASV-AUVの使い方 ASV-AUV operation



Marine resource exploration with multiple AUVs

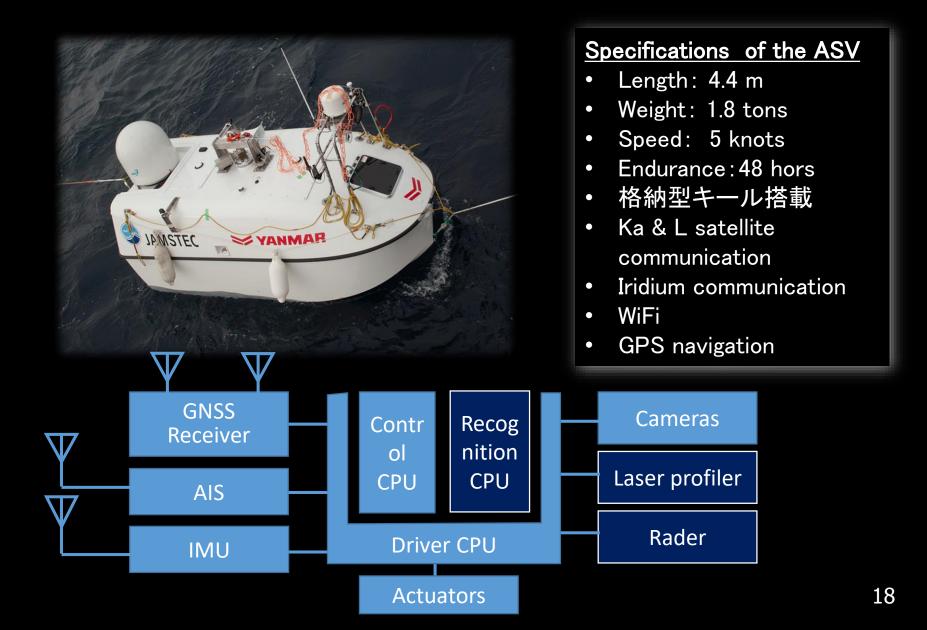


Pipeline inspection



Sonar Laser Scanner Camera

JAMSTE's Robotic Boat



運用化への課題 Technologies improvement needed

- 1. 測位 (Positioning) 特に海中が難しい GNSS-INS-Doppler velocity meter hybrid navigation
- 2. 他船舶や海洋構造物との**衝突**回避方法(How do you avoid collisions?)
 - i. 自動認識 (Automatic recognition)→ Probability of misjudgment?
 - ii. 遠隔監視 (Tele-monitoring) → Mandatory twenty-four-hour supervision?
- 3. 信頼性(Reliability)
 多数のロボットを同時に利用していくために、どのような信頼性基準が必要か?

運用化への課題 Regulations

- 海上衝突予防法
 The Act for Preventing Collisions at Sea is the most important.
- 海上・海中ロボットのルール作りでは漁協の意見が重要
 It is important to reflect views of fisheries cooperative association on the rules.
- 日本国内には未だ無人船のルールが無い
 There has been no progress in making revisions to existing laws to deal with ASVs in Japan.
- 無人船のルール化に当たっては、無人船のメリットが出るようなレギュレーションが必要
 The regulation to be revised must have the merit of ASVs compared to manned ships.

ボートサイズ無人船(ASV)実用化にむけて

Toward the realization of ASVs in Japan

Standardization & Test sites 県や国が取組 Regulation 民間団体から 要望

Market 国プロと 民間による開拓

Practical applications of ASV/USV

insurance 民間が取組

Commercialization 数社の民間 が取組 Technology development 国研、民間が 取組

個別な取り組み individual actions



相互協力による統一的な取り組み Unified actions

END